

BIOMIXER BM330

Service Manual

Ljungberg & Kögel AB

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Important

This Service Manual is written for the service personnel (technicians) responsible for service and maintenance of Biomixer BM330. It gives a detailed description about the BM330 soft- and hardware, explaining how it works and how to run the built-in testprogram.

Note! It is important that the service personnel has been trained and approved by Ljungberg&Kögel before opening the instrument or making any repair operation, if not, the warranty may be invalid.

L&K recommend exchange of complete parts as specified in "Spare Parts List" in Operator's Manual instead of replacing discrete components.

For operating instructions and Spare Parts List see BM330 Operator's Manual.

Abelko Innovation is committed to develop high-quality equipment and technical services to all our customers. We welcome any inputs on technical issues that are encountered so that they can be resolved quickly and in the most appropriate manner. Please submit your comments/feedbacks through your local distributors or alternatively email us directly at info@abelko.se

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General technical description.

BM330 is controlled by an 8 bit microprocessor 8052 with external 64 kbyte prom for program execution and 32kbyte CMOS RAM for data storage. A realtime watch (RTC) Dallas DS1302 keeps the time and date. All settings, ID, calibration constants etc. are stored in a non-volatile serial Eeprom. A backup super capacitor keeps the data RAM and RTC with power when internal battery is flat or during exchanging.

It is powered by an internal lead-acid battery 12V/3,5Ah and the battery is recharged with an external battery charger with a constant voltage of 14.0VDC and maximum current 0.8A.

The weighing is done by a loadcell, and a bridge amplifier amplifies the signal and an A/D-converter converts the analog signal to a digital 12 bit word which is serially read by the CPU.

The mixing tray is operated by an AC-driven synchronous motor. The 50Hz AC is generated by software in the CPU and transformed to 24VAC waveform by a transformer.

The clamp is operated by a linear stepmotor controlled by a controller IC TCA 3727.

The keyboard is a membrane key matrix and the display is a 2x20 LCD with internal character generator.

There is one RS232 serial communication port for a PC or a barcode reader and one RS485 port for LAN communication with up to 31 mixers connected together, transmitting collected data to a registration PC.

Optionally an external display with large figures for collection volume can be connected to the mixer.

Detailed technical description.

Software

Development environment

The program is written mainly in ANSI C, with MCU specific extensions for Intel 8051 family.

Compiler is IAR:s ICC8051, ver 5.12H.

Assembler is IAR:s A8051, ver 2.03.

Linker is IAR:s XLINK, ver 4.46L.

Debugging has been done using Nohau's Emul51 emulator, but also by using a special program version compiled for Borland TurboC ver 3.00, containing software simulation of some of the hardware.

Memory allocation

Setup

Non volatile setup parameters are saved in EEPROM memory. Each time a parameter is changed and the menu is left, the parameter is saved to EEPROM and a new checksum is calculated on the entire EEPROM memory. Setup parameters can be viewed or changed in the setup or test menus only.

When the program is started, the EEPROM area is mirrored to RAM-memory for easy and fast access. If a checksum mismatch is discovered during this process a setup error message is displayed and default parameters are used.

Data

Information concerning each collection is saved in capacitor (BUC) backedup RAM memory.

This memory is not checksum protected, but an area is reserved for a "sentinel" value that is used to determine if data has been lost, due to a long period without mains or battery supply.

If the memory should be detected as lost during startup it is erased and the sentinel value reinitialized. During this erase a hardware RAM check is also performed, and a data error message is displayed. Hardware RAM check can also be done in the test menu.

If the memory is lost during operation, a data error message is also displayed, but the memory is not erased until a restart is done.

If a powerfail should occur during a critical write of data, i.e. increase of an index value that isn't written in an atomic process, it could result in scrambled data.

To prevent this the external watchdog circuit generates an early warning high priority powerfail interrupt. Prior to each critical writes of data the powerfail interrupt is disabled, the write is done, and the interrupt is enabled again. The interrupt routine is simply a delay that prevents the normal program to run until the voltage is lost. This ensures that a critical write is made in an atomic, uninterruptable process.

Functional description

Basic program components block diagram

Initialization

Continued collection

(If powerfail during collection)

See *NEW* or *START* at level prior to powerfail

Test program

SETUP (boot) – Start
test program

Erase memory program

NEW + SETUP (boot) –
Start EEPROM + RAM erase program

NEW + RESET (boot) –
Start RAM erase program

Main program

NEW –
Start new barcode collection

Scan barcodes

Collect blood

Collection ready

Scan barcodes

Send collection data

START –
Start new collection

Collect blood

Collection ready

Send collection data

SETUP –
View and change
setup parameters

SET –
Toggle between 2
preset volumes

INC / DEC – Change
current preset volume

SEND –
Send collection information to
PC-program

PAUSE –
Continuous measuring
without registration

CLAMP –
Open/close clamp

RESET –
Park the tray

Sub programs

Keyboard scanning
(irq)

Tray AC-motor
driver (irq)

Clamp step-motor
driver

Display driver

Error handler

EEPROM
routines

External display
driver

A/D routines and
measuring

RTC routine

Serial communication (irq)

Configuration

Barcode reader

Collection data

Electronic potentiometer
routines

Buzzer level

Taring

Timer routines
(irq)

Powerfail routine
(irq)

Start, initialization after power on

At power on system registers are initialized, i.e. stack pointer etc.

Then the display is initialized and the text "Initializing..." is displayed during further startup procedure.

BUC backuped RAM memory is tested and re-initialized if lost.

C-variables are initialized.

EEPROM parameters are mirrored to RAM or set to default values if a checksum error was discovered.

If erasing memory should be done on keyboard boot command it is done now.

Electronic potentiometers are initialized.

Clamp is initialized.

If continued measuring should be done due to powerfail it is done now.

The tray is moving one mixing cycle.

If function testing should be done on keyboard boot command it is done now, otherwise the standard menu is displayed.

The program is now ready for keyboard commands.

Driving the AC-motor

The AC-motor, used for tray mixing cycles, is managed by an interrupt routine which generates 50 Hz pulses.

If, for some reason, the motor wheel never reach its home position (tray jammed etc.) a motor error is displayed.

Driving the clamp

The clamp is operated by a stepmotor which is controlled by a program subroutine.

At power up, the clamp is reset by setting its position counter to "closed" (despite its actual position) and then run it to "open".

If the clamp was already open this operation will have no effect, but to make sure for the program that the position is indicated correctly.

Battery capacity

The battery capacity is constantly monitored each 5 seconds, except for the moments when the tray motor is running.

If the capacity is too low another collection cannot be started, but the current one can be finished.

Weighing, reading the A/D

The A/D converter is used to read the amplified value from the loadcell on one channel.

The other channel is used to measure battery voltage.

The loadcell value is converted to volume or weight, due to how it is calibrated.

During collection, the filtered difference between values at each weighing cycle is also converted to flow per minute.

Scanning the keyboard

The keyboard is scanned on interrupt and saved in a keyboard buffer.

If a key is pressed longer than 0.5 seconds it is repeated.

The keyboard buffer is then polled each program loop.

Updating the display

The display is initialized during startup.

At each program loop the display buffer is written to the display.

Reading the RTC

The RTC (Real Time Clock) is read every new second in the program loop.

The clock value is used for timestamp collection data and keep track of collection time, collection alarm intervals etc.

If the time read from the RTC should be invalid a clock error is displayed.

Automatic taring

Prior to each collection an automatic taring sequence is performed.

It is done by adjusting the electronic potentiometer for taring until the relative volume (with empty bloodbag on tray) reads 0 ml.

(The absolute volume is then about 100 ml if adjusted and calibrated correctly. This means the relative volume can show negative values down to -99 ml).

If the relative value of 0 ml for some reason cannot be reached a tare error is displayed.

The manual offset adjustment in the test menu is done to give the electronic potentiometer the maximum possible range at each direction.

Buzzer volume

Buzzer volume is set in the setup menu. It is controlled by an electronic potentiometer which can be set to values between 0 to 31.

Note that a value less than 12 may cause the buzzer to stop beeping.

Setup

In the setup menu a number of non volatile EEPROM parameters can be viewed and changed.

Each time a parameter is changed and the menu left, the parameter is saved to EEPROM and a new checksum is calculated.

If the EEPROM has a faulty checksum during initialization a setup error is displayed.

Calibration

The calibration sequence in setup menu is done to establish the coefficient for converting A/D bit value to volume (or weight).

This is done by first perform a tare to establish zero point and then adding a weight of 472g to calibrate for bit value to volume.

Data storing and sending

Collection information, including barcode readings, are stored in BUC backed RAM. It can be transmitted to the information PC at the end of each collection, or at a later time.

Program verification

General

- Programming.
- Simulation of the target system in Borland C.
- Emulation on Nohau EMUL51.
- PROM-testing.

Simulation of the target system

Each menu and as much as possible of other functions has been tested during development to find as many bugs as possible during an early stage.

This has been done by compiling a program version for simulation, where keyboard and display has been redirected to a PC keyboard and monitor.

This simulation tests includes:

- All menus, except erase memory.
- Error handling, by introducing faked error conditions.
- Barcode reading by introducing faked barcode messages.
- Display routines, at high level.
- Keyboard routines, at high level.
- Change preset collection volume.

Emulation on Nohau EMUL51

To test routines that isn't easy to test with a simulation program, and to catch bugs in all code segments and in hardware, an emulation test has been done:

- Communication from configuration PC by receiving configurations.
- Communication from barcode reader by receiving barcodes according to different configurations.
- Communication to collection PC by sending collections.
- Communication (general) by running test program for communication.
- Collection test by applying 5g weights until the different collection modes has been reached. This includes test of flow alarm, time alarm and measuring.
- Setup memory test, by using memory test routines and checking that values remain after powerfail.
- Clamp motor function by visual inspection in program and test routines.
- Tray motor function by visual inspection in program and test routines, and by preventing the wheel to reach home position (motor error test).
- Memory erase programs, by running them and check result in emulator memory and setup menu parameter values.
- Powerfail interrupt, by variable input voltage and setting a breakpoint in the interrupt routine.
- Battery capacity, by variable input voltage and compare display readings to voltmeter readings.
- RTC, by setting and reading time in test menu and collection menu.
- Timer interrupt, by breakpoint settings and time measuring between breakpoints.
- External display, by measuring on CPU pins when running its test program.
- Taring, by compare measured values from voltmeter (A/D-level and electronic potentiometer level) with theoretical expectations.

- Calibration, by comparing measured values from voltmeter (A/D-level) with theoretical expectations.
- Stack check, by emulator memory control.

Prom testing

- Every menu and program mode has been executed.
- Two bloodbags connected with a tube, of which one contained colored liquid with the density of blood, has been used to simulate donations.

Hardware

See schematics on page 20

Microprocessor and memory

BM330 is controlled by an 8 bit microprocessor 8052 with external 64 kbyte prom for program execution and 32kbyte CMOS RAM for data storage. The oscillator runs on 11.0592 MHz, a frequency chosen to suit communication bit rate generation by internal timers.

Data backup

Data CMOS RAM have low standby current $< 1\mu\text{A}/3.5\text{V}$ and is, together with the RTC, back-uped by a 0.1F super capacitor C19. The battery switchover circuit IC20 (Max 691A) automatically switch over to backup capacitor when +5Vcc supply drops below 4.6V. During this time IC20 also turns off chip select signal CERAM to avoid accidentally writing in RAM during power down. IC 20 also senses the battery voltage before the 5V-regulator to get an early warning on Pfail output when power is disappearing. This PFAIL signal is connected to the highpriority INT0 interrupt to the CPU.

Serial synchronous bus (SPI)

A serial bus with SOUT, SIN, SCLK is used to communicate with the 12 bit A/D-converter IC5, serial EEPROM IC18, where the setup and calibration parameters are stored, the RTC IC19, the electronic potentiometers IC4 for offset adjustments and IC 17 for buzzer volume and finally the optional external display. It runs with ca 500kbps clockpulses and each circuit (function) is selected by the chip-select decoder IC6 selecting CSPOT, CSEXT, CSBIP, CSAD, CSE2 and CSCLK respectively with CPU pin P1.0, P1.1 and P1.2 giving the address.

I/O ports

There are 4 parallel I/O-ports connected to the databus. IC12 is an output for buffering data written to the display together with the buffered signals A0, A1 and OUTAX. IC 13 is an inport for reading the keyboard matrix scanned with output IC14. IC14 also turns on and off the buzzer and gives the 50Hz signals to the AC-driven asynchronous motor for tray movement. IC15 is the output for the stepmotor controller IC16. The chip-select signals to all this I/O-ports are created by IC8 and are memory mapped for addresses above RAM adress, i.e. from 8xxxH.

Tray motor movement control

The 50 Hz driving the AC-motor is generated by the IC14 pin 5,19 signals MD1,MD2. They are pulsing 50Hz with a phase difference of 180 dgr. Transistors T1 and T2 are amplifiers and level converters and transformer TR1 transform the 12V signal on the primary side to 24 VAC at the secondary side, driving the motor. The 3:rd phase is generated by the bipolar capacitor C30.

"Home" switch

A reed switch mounted on the motor plate works as a position sensor and are actuated by a small magnet glued in a hole in the driver wheel. When the driver wheel enters the "home position" where the tray goes free from the roller, i.e. is in the weighing position, the switch is closed by the magnet and the signal is read by the inport IC13 and signals to the CPU which immediately stops the motor and makes a weighing. See spare parts list in Operator's Manual for mechanical details.

LCD contrast potentiometer

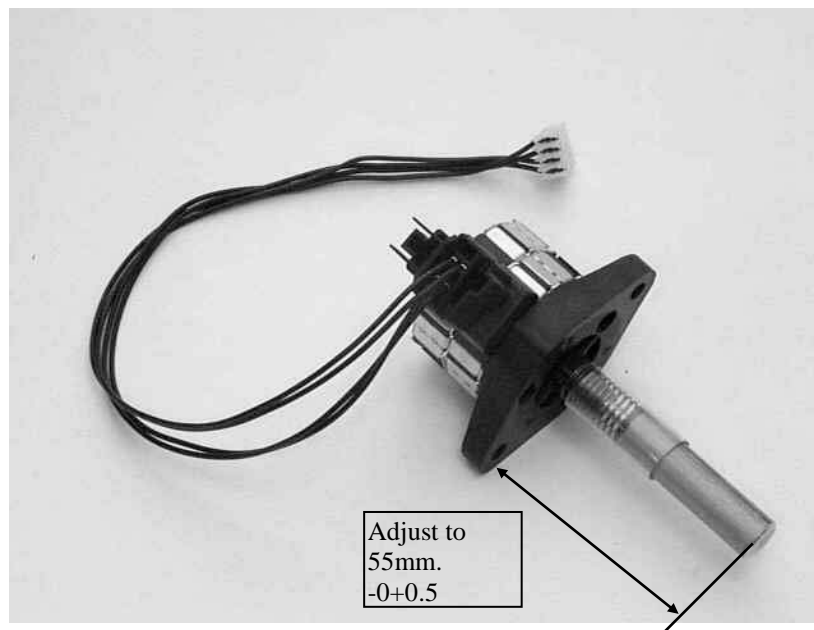
The LCD contrast can manually be adjusted with the potentiometer TP3.

Buzzer volume

Volume level is adjusted by an electrically programmed potentiometer and adjustments are made from "Setup menu", see Operator's Manual for details. The Eepot is controlled by the SPI-bus.

Clamp linear stepmotor driver

The clamp is controlled by a linear stepmotor which is driven by IC16, a Siemens TCA3727 driver. For the clamp to close properly the distance from the top to the base must be 55.0-55.5 mm in closed position, i.e. max out, see picture below:



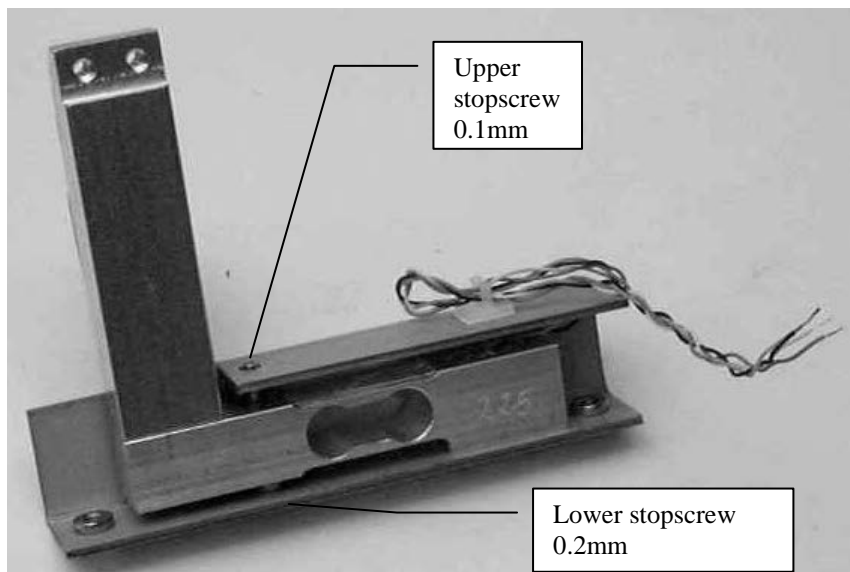
Load cell and amplifier

Load cell 325-3 is a full bridge cell given a signal of ca 1.5 mV/Kg. The origin offset (built in offset from loadcell production) is manually adjusted with the potentiometer TP1 to a level from A/D-converter corresponding to ca 100 ml (ca 360 mV measured at IC5 pin 4) at production test. During this adjusting the electronically controlled potentiometer IC4 is in the middle (neutral) position. When BM330 makes the taring process it adjusts the IC4 potentiometer back to ca 100ml. (This is done with the empty bloodbag on the tray). This value is then referred to as the zero-value and deducted from the continuous readings when the blood is collected.

The reason for this electrically adjustment of balance is to give a very dynamic adjustment range insensible of tare weight or if the loadcell has been deformed by tough treatment during transportation or otherwise.

The amplifier consist of two op-amps connected in a way that eliminates the input offset voltage and has a gain that gives a 0-5V signal for a weight of ca 0-1360g. The gain can be adjusted by potentiometer TP2 and adjustments should be made according to instructions in the Operator's Manual. See also testprogram number 3 and 4 in this manual.

The loadcell is protected by stopscrews for both lifting and pressing overloading. The upper stopscrew shall be adjusted to 0.1mm distance and the lower stopscrew shall be adjusted to 0.2 mm, use a thickness gauge for measuring. Adjustments can be done with the loadcell loosened or with the PC-board loosened. The lower stopscrew is accessible from a hole in the chassis bottom plate. See figure below:



RS232 serial communication port

This port is used for the barcode reader with the power supply +5V and gnd connected to p9 and p5 in the 9-pole male dsub connector. See complete wiring in BM330 Operator's Manual. It is very important that the used barcode reader has a compatible connection, otherwise the mixer or the barcode reader may be damaged. The barcode reader current consumption must be max 60mA in average or else the battery operation time will be reduced.

Note! Always use barcode-readers recommended by Ljungberg&Kögel

The RS232 port is also used by the configuration PC when setting up the mixer for network operation. See Operator's Manual for details.

RS485 serial communication port

This port is a multidrop LAN "Local Area Network" connector for connecting 1-31 mixers together in a LAN to a common registration PC for registration of blood collections. It follows the RS485 standards and the connector is a RJ12. See Operator's Manual for network details.

External display

The connector is a RJ12 connector with +12V power out and parts of the SPI-interface, SOUT, SCLK and CSEXT. Information to the display is shifted out in a serial bitstream with ca 500kbps once a second.

Power supply and voltage regulators

The mixer is powered by an internal lead-acid battery of 12V/3.5Ah recharged by an external constant battery charger. The battery charger can supply the mixer even if the battery is flat or if the battery is removed.

Battery voltage is measured by the A/D converter and remaining power is shown on display during power up.

Note! When battery charger is connected the remaining power will always display 99%.

The battery is supplying the backup capacitor with a small maintenance current to keep the RTC and RAM with power during storing and transportation and the battery is protected from being completely emptied by the zener diode Z1. The maintenance current drawn from the battery is less than the battery selfdischarge current.

Wires and components are protected from hazardous current flow in case of a shortage by a selfrecovery PTC termistor PTC1.

There are two voltage regulators: REG1 for +5V digital supply and REG2 for +5V analog supply, to avoid digital noise in the measuring circuits. The groundplane is also separated in an analog groundplane, marked with a dotted line in amplifier section of circuit diagram, and a digital groundplane for the rest of PCB.

Running the testprogram

A built in testprogram can be run to verify BM330 functions. The testprogram is started when the SETUP key is pressed during power up.

When testprogram has started (takes about 3-4 seconds) the display shows:

TEST AUTOMATIC

TEST MANUAL

With "+" and "-" keys you can choose Automatic or Manual test. Confirm with a press on SETUP. A press on RESET ends the testprogram and the ordinary main menu is shown.

If Automatic test is selected the test sequence will immediately start with test1: Displaytest, and continue with the next test after a new press on SETUP. When all 15 tests are done you will be back to the startmenu as above.

If Manual test is selected with the press on SETUP, you can now select the testno. with the keys "+" and "-" and confirm with SETUP. The testnumbers are listed below for respective testfunction. Testfunction ends with a press on SETUP and a new Manual test number can be selected with the keys "+" and "-" or continue with the next test by pressing SETUP. Manual test is ended with a press on RESET and the ordinary main menu is shown.

TEST MANUAL
1 DISPLAY TEST

1 Displaytest.

All segments of row 1 are turned on in 0.5 sec and then all segments on row 2 are turned on alternately. The test is done to verify that display and connections are ok. If necessary the contrast can be adjusted, see Operator's Manual for details. The test is ended with SETUP

#####

2 Keyboardtest.

Keyboard is checked by pressing each key and the display shows the key function. End by pressing "NEW" and "SETUP" simultaneous.

2 KEYBORD TEST
SETUP

3 Offset (zero) calibration.

This is a check of the loadcell origin offset adjustment done with the inside potentiometer TP1. The electronic potentiometer IC4 is programmed in the middle position (after pressing START) and the value shown on the display should be ca 0-200 with the empty tray on the loadcell shaft. TP1 can be adjusted (the cover must first be lift off) to the nominal value $+100 \pm 5$ ml. The value on display is the actual weight converted to ml (/1.06) affecting the loadcell and is continuously updated.

Note! This origin offset adjustment is normally only need to be done when the loadcell has been replaced or if it has got a hard blow making it change the value radical, there is no need to readjust TP1 if the value is 0-200 for the weight of the empty tray. End with SETUP.

3 CALIBRATION OFFSET
PRESS START

3 OFFSET VALUE
95 (100)

4 Gain calibration and adjusting.

Gain calibration starts with an automatic taring (after pressing START) and then the weight on the tray is showed on display. Put the reference weight of 450ml (477g) on the tray with the opening in the reference weight placed over the positioning peg on the tray for best accuracy.

Note! Always use reference weights from Ljungberg&Kögel for best accuracy.

The reading should be $450 \pm 5\%$ but notice that the reading is the rough value without the software automatic calibration!

If out of limits adjust the GAIN potentiometer TP2 until the reading is $450 \pm 5\text{ml}$, remove the reference weight and make a new taring by pressing SETUP-“-“ (to go back to GAIN calibration menu) – SETUP and after that START again. Put the reference weight back and repeat adjustment until the value is within $\pm 5\text{ml}$. End with SETUP.

Note! Always end with automatic calibration, without manually adjusting the gain, to get the correct software calibration factor. See Operator's Manual Setup functions "Calibration".

4 CALIBRATION GAIN
PRESS START

GAIN VALUE
0 (450)

5 Clamp test.

This test closes the clamp, waits 0.5 sec and then opens the clamp, waits 0.5 sec and so on. Check that the closing is complete.

Note! Never leave the test in this mode for a longer time i.e. more than 10 minutes, since the step motor will get overheated and may be damaged.

Test is ended by SETUP and the clamp will be left open.

5 CLAMP TEST
CLAMP OPEN

6 Motor and "home" position sensor test.

One mixing cycle is done, then a stop in the weighing position for ca 0.5 sec, a new cycle is done, stop, and so on. Check that the motor with the gearbox is running nice and smoothly. Test is ended with SETUP.

6 MOTOR TEST

7 Battery test.

This test shows the battery voltage on display. The measuring accuracy is $\pm 0.1\text{V}$ and can be adjusted with TP4.

7 BATTERY 12.00

8 Setting of buzzer volume.

This test checks the electronic potentiometer IC17 and the buzzer connection. The potentiometer is programmed in its middle position (15) and the buzzer starts beeping when "+" or "-" is pressed. Check that the volume can be

increased with "+" and decreased with "-" and the last value programmed when leaving this test will be the set buzzer volume.

Note! Setting too low value, <12, may cause the buzzer to stop beeping.

Test is ended with SETUP.

```
8 BUZZER VOLUME 15
```

9 Test of external display output.

CSEXT (chip select extern display), SOUT (serial out) och SCLK (serial clock) is going to high level (5V) for 0.3 sec, then low level (0V) for 0.3 sec in sequence. A special testequipment with leds connected to the output is needed to detect the outputs. Test ends with SETUP.

```
9 PORTTEST EXT.DISP.
```

10 Communication test RS232.

A loopback test is done and a special testequipment is needed with DTR connected to CTS and TxD connected to RxD. DTR and TxD are toggled and read back via CTS and RxD. Status is shown with ERROR or OK.

Test is ended by SETUP.

```
10 PORTTEST RS232  
TXD ERROR RTS OK
```

11 Communication test RS485.

A loopback test is done and sent data is checked that it also is received data.

Note! This test requires no testequipment but is also limited because it doesn't checks the physical capacity of the RS485 driver. Test is ended by SETUP.

```
11 PORTTEST RS485  
TXD OK
```

12 Clocktest.

In this test the RTC time and date are continously updated. The time and date can also be set by pressing "+" , "-" and "SET"). Test is ended by SETUP.

```
12 CLOCK  
22/3 1997 16:30:13
```

13 RAM-test.

This test checks all memory cells in RAM without changing the stored data. Testresult is shown on row 2. Test is ended by SETUP.

```
13 MEMORYTEST RAM  
OK
```

14 EEPROM-test.

This test checks all memory cells in EEPROM without changing the stored data. Testresult is shown on row 2. Test is ended by SETUP.

```
14 MEMORYTEST EEPROM  
OK
```

15 EPROM-test.

This test calculates the checksum for EPROM and shows it on the display. The value should be the same as marked on the EPROM label. Test is ended by SETUP.

```
15 MEMORYTEST EPROM  
xxxx
```

Special memory commands

The following memory commands can be useful if there has been scrambled data in memory causing the BM330 to fault or malfunction, e.g. problem with starting up.

Data memory clear

Data memory (RAM) is cleared by pressing NEW and RESET during power up. Display will show:

```
ERASE DATA?  
YES:RESET    NO:SET
```

A press on RESET will erase all data memory.

Warning! All collected data will be lost.

Data and setup memory clear

Data (RAM) and Setup (EEPROM) memory is cleared by pressing NEW and SETUP during power up. Display will show:

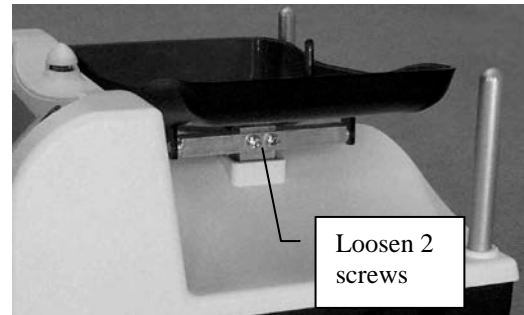
```
ERASE SETUP+DATA?  
YES:RESET    NO:SET
```

A press on RESET will erase all data memory and setup memory.

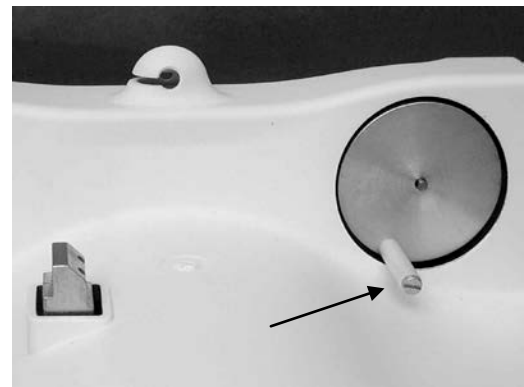
Warning! All setup data e.g. flow alarm, time alarm, etc. will be set to default values. All configuration data will be lost and has to be reprogrammed and a new calibration must be done.

Dismounting the BM330

1. Loosen the 2 screws holding the tray, and lift off the tray.



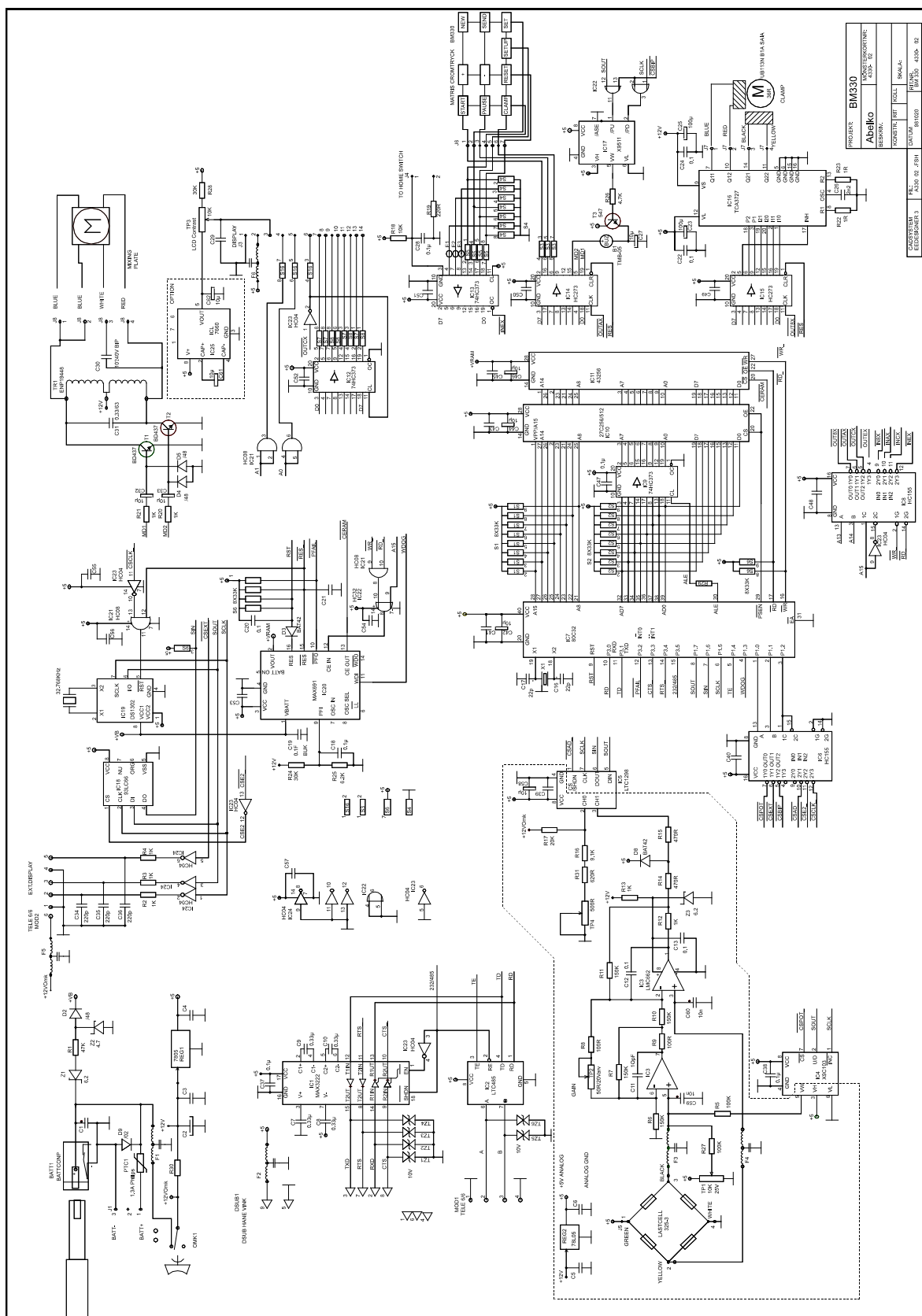
2. Loosen the screw with roller.



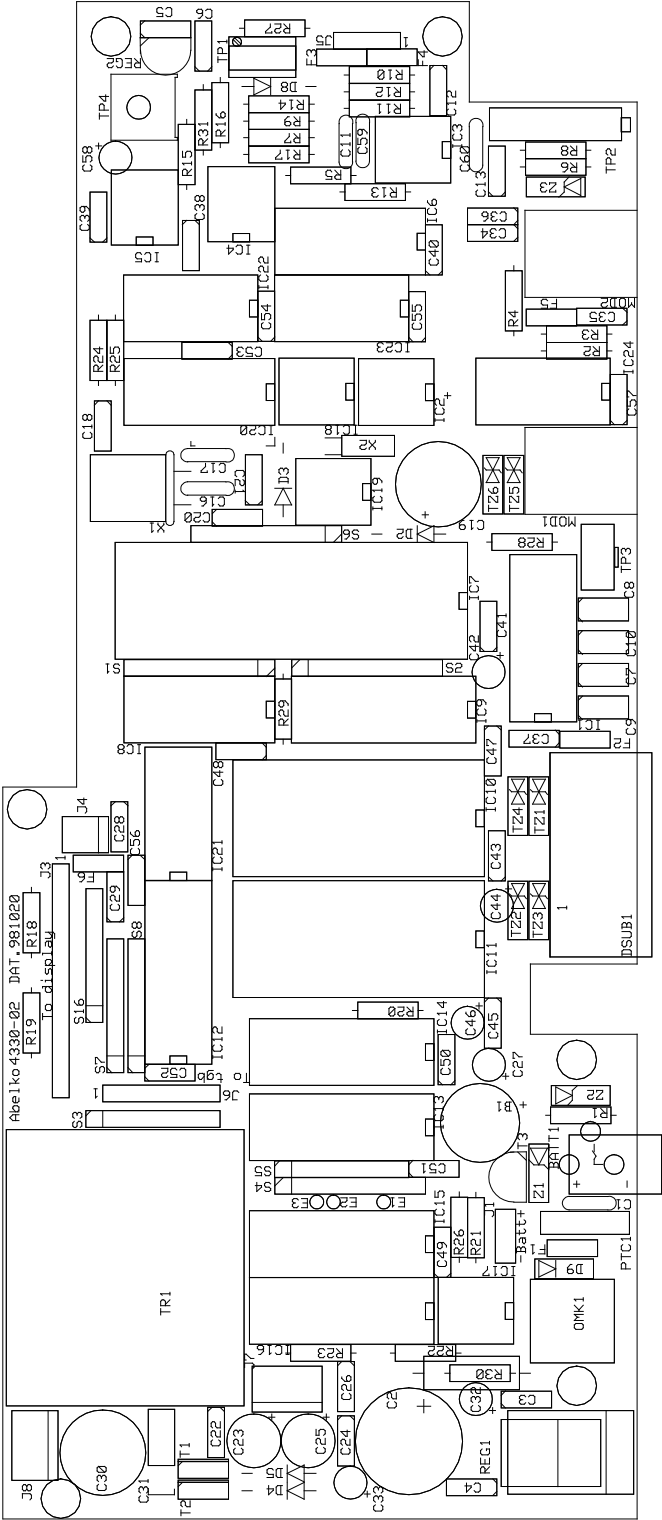
3. Loosen the 4 screws holding the cover, marked with arrows on figure. Lift off the cover.



Circuit diagram



Component placement



Test protocol (Production final test)

This is the test protocol used for the final test in factory.

This document is referring to the *BM330 test procedure*.

Date	
Name	
Serial number	

<i>Reference: BM 330 test procedure</i>					
§	Description	Read value	OK	ERR	Remarks
1	Factory software version				
2	Check of basic functions				
3	Cover, tray assembly				
4,5	Overload and seesaw motion				
6	Calibration,tare before burn-in				
7	Burn-in				
8	Tare drift after burn-in (ml)				
6.1	Display				
6.2	Keyboard				
6.3	Offset				
6.4	Gain				
6.5	Clamp				
6.6	Motor				
6.7	Battery				
6.8	Buzzer				
6.9	External display output				
6.10	RS-232				
6.11	RS-485				
6.12	Clock				
6.13	RAM				
6.14	EEPROM				
6.15	EPROM				
10	Calibration after burn-in				
12,13	On line registration				
14	Custom install				
15	Check calibration (ml)				
16	Final inspection				
17	Type plate				

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